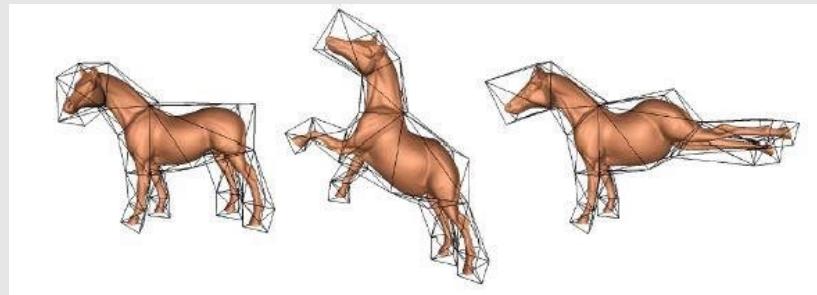


# **Advanced Interpolation**

# Application of Interpolation

## *Cage-based deformation*

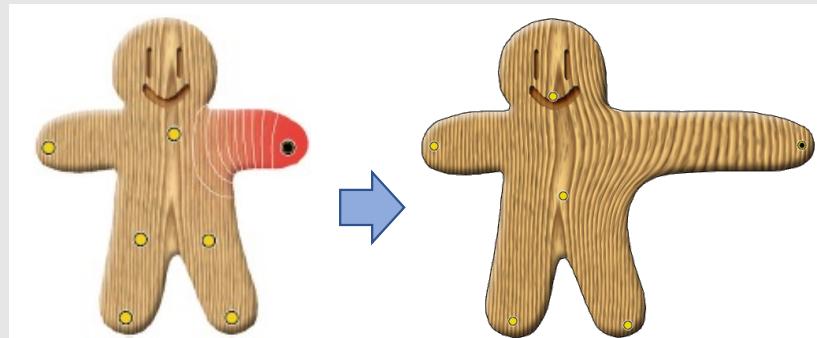
Interpolating positions in a polygon



[Ju et al. 2005]

## *Rigged-based deformation*

Interpolating rigging weight inside mesh

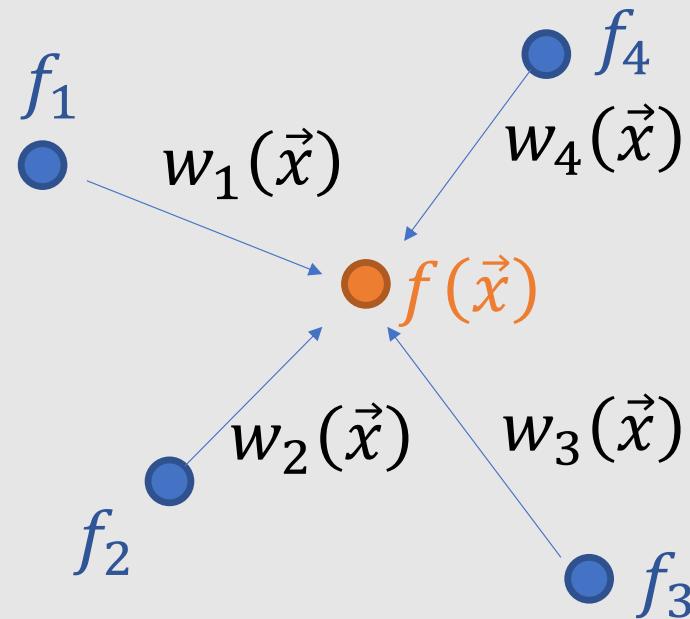


[Jacobson et al. 2005]

T. Ju, S. Schaefer, and J. Warren. *Mean value coordinates for closed triangular meshes*. SIGGRAPH 2005

A. Jacobson, I. Baran, J. Popović, and O. Sorkine. *Bounded biharmonic weights for real-time deformation*. SIGGRAPH 2011

# What is the Requirements for the Weights?



$$f(\vec{x}) = \sum_i w_i(\vec{x}) f_i$$

- Weight  $w_i(\vec{x})$  must change smoothly  
  $w_i(\vec{x})$  is a harmonic function (e.g., solution of Laplace equation)

# The Property of Laplace Equation

By definition Laplace equation has no peak ( $\nabla^2 \phi = 0$ )

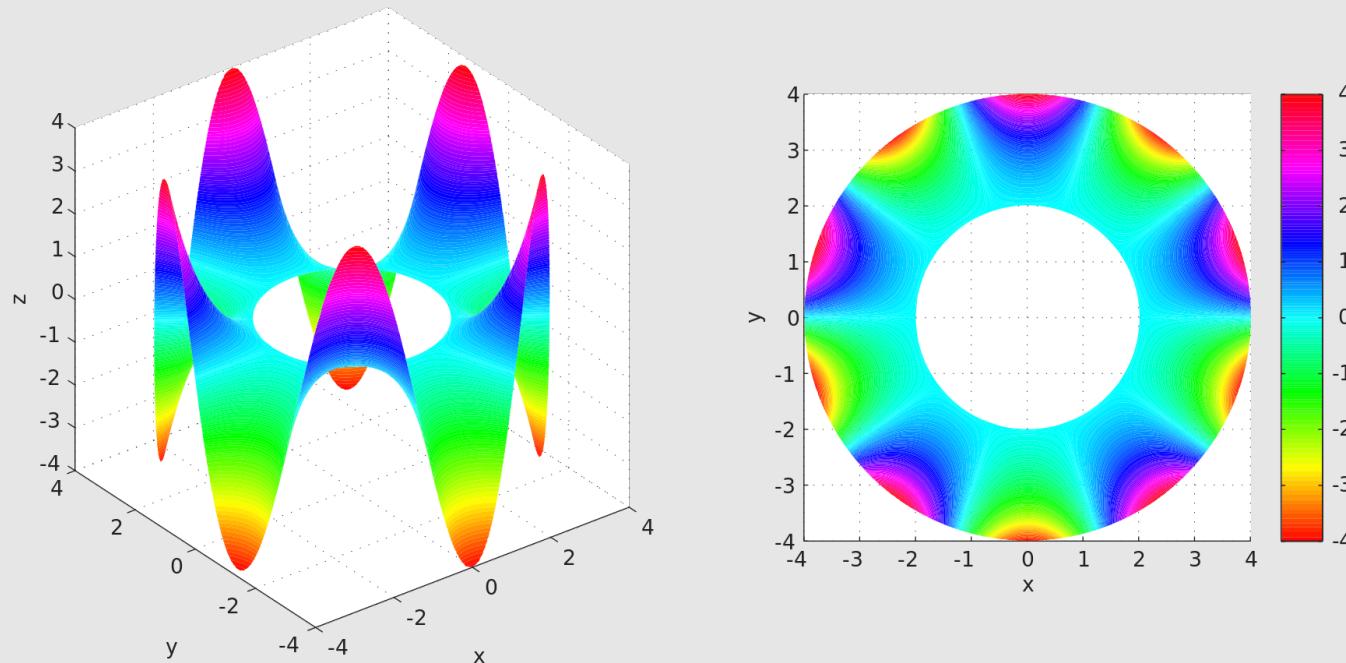


Image Credit: Fourthirtytwo @ Wikipedia

# Laplace Equation: Mean Value Property

The solution of the Laplace equation at  $\vec{x}$  is average of the solution on the circle around  $\vec{x}$

$$f(\vec{x}) = \frac{\int_{\vec{y} \in \mathcal{B}(\vec{x}, r)} f(\vec{y}) d\vec{y}}{\int_{\vec{y} \in \mathcal{B}(\vec{x}, r)} d\vec{y}}$$

for arbitrary  $r > 0$

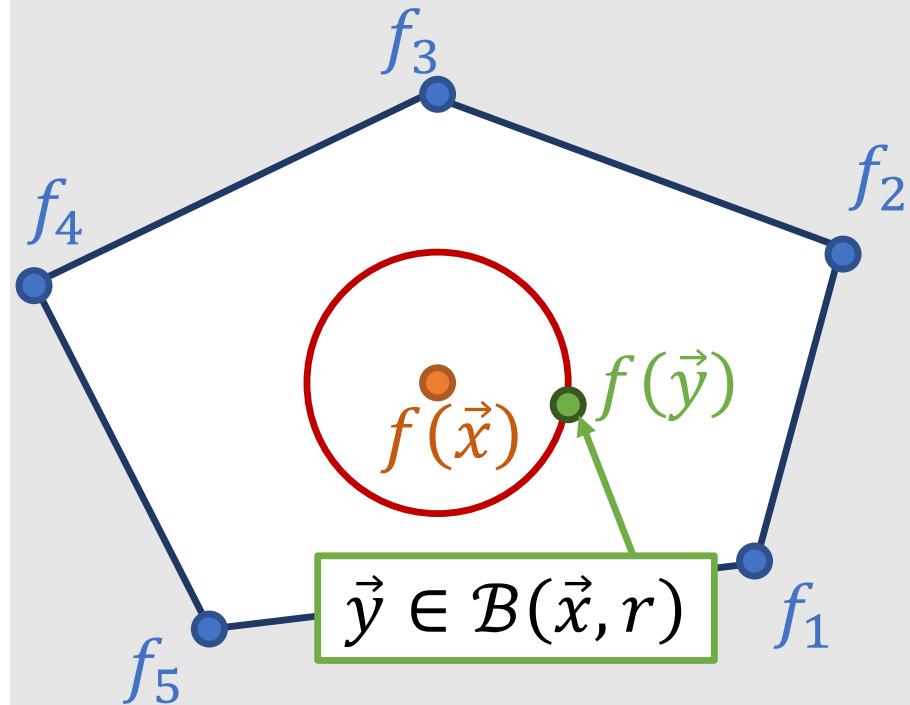
Solution at  $\vec{x}$

The sum of the solution on  $\mathcal{B}(\vec{x}, r)$

circumference of  $\mathcal{B}(\vec{x}, r)$

# Mean Value Coordinate [Floater 2003]

- Interpolation inside polygon using the mean value property

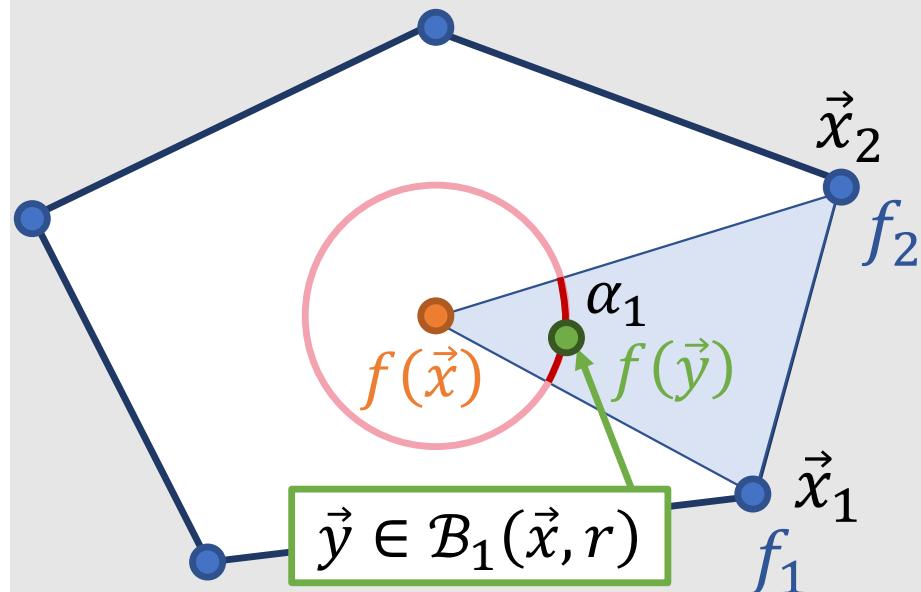


$$f(\vec{x}) = \frac{\int_{\vec{y} \in \mathcal{B}(\vec{x}, r)} f(\vec{y}) d\vec{y}}{\int_{\vec{y} \in \mathcal{B}(\vec{x}, r)} d\vec{y}}$$

$2\pi r$

# Mean Value Coordinate [Floater 2003]

- Assume  $f(\vec{y})$  is a **linear interpolation** inside the triangle  $(\vec{x}_1, \vec{x}_2, \vec{x})$



$$f(\vec{y}) = L_1 f_1 + L_2 f_2 + (1 - L_1 - L_2) f(\vec{x})$$



Integration on the arc  $\mathcal{B}_1(\vec{x}, r)$

$$\int_{\vec{y} \in \mathcal{B}_1(\vec{x}, r)} f(\vec{y}) d\vec{y}$$

$$= r \alpha_1 f(\vec{x}) + r^2 \tan\left(\frac{\alpha_1}{2}\right) \left[ \frac{f(\vec{x}) - f_1}{|\vec{x} - \vec{x}_1|} - \frac{f(\vec{x}) - f_2}{|\vec{x} - \vec{x}_2|} \right]$$

# Mean Value Coordinate [Floater 2003]

- Closed-form approximate solution in a convex polygon

$$f(\vec{x}) = \frac{\int_{\vec{y} \in \mathcal{B}(\vec{x}, r)} f(\vec{y}) d\vec{y}}{\int_{\vec{y} \in \mathcal{B}(\vec{x}, r)} d\vec{y}} = \frac{1}{2\pi r} \sum_{e \in \text{Edges}} \int_{\vec{y} \in \mathcal{B}_e(\vec{x}, r)} f(\vec{y}) d\vec{y}$$



$$\int_{\vec{y} \in \mathcal{B}_e(\vec{x}, r)} f(\vec{y}) d\vec{y} = r \alpha_e f(\vec{x}) + r^2 \tan\left(\frac{\alpha_e}{2}\right) \left[ \frac{f(\vec{x}) - f_e}{|\vec{x} - \vec{x}_e|} - \frac{f(\vec{x}) - f_{e+1}}{|\vec{x} - \vec{x}_{e+1}|} \right]$$

$$f(\vec{x}) = \frac{\sum_{p \in \text{Points}} w_p f_p}{\sum_{p \in \text{Points}} w_p},$$

$$\text{where } w_p = \frac{\tan(\alpha_p/2) + \tan(\alpha_{p+1}/2)}{|\vec{x} - \vec{x}_p|}$$

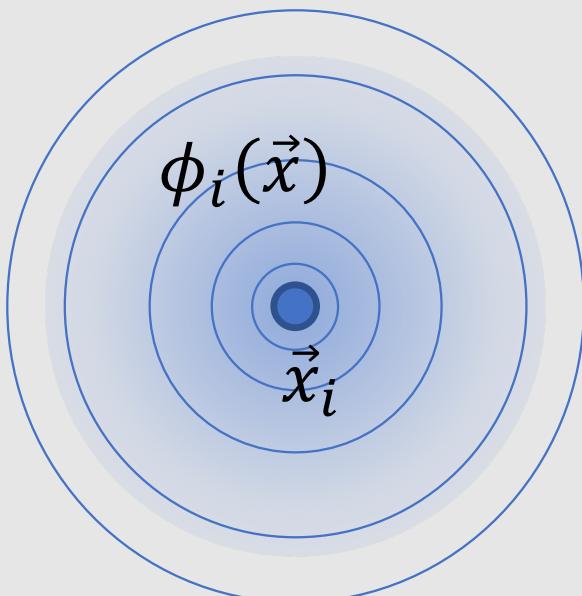
# **Radial Based Function Interpolation**

# Radial Based Function

(放射基底関数)

- The function depends only on radius (rotational symmetry)

$$\phi_i(\vec{x}) = \phi(|\vec{x} - \vec{x}_i|)$$



The contours line of  $\phi_i(\vec{x})$   
are circles centers at  $\vec{x}_i$



# Radial Based Function

(放射基底関数)

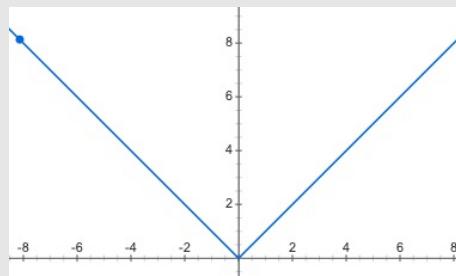
- The function depends only on radius (rotational symmetry)

$$\phi_i(\vec{x}) = \phi(|\vec{x} - \vec{x}_i|)$$

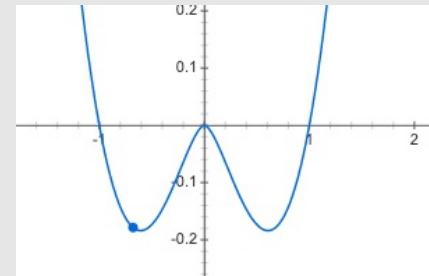
Typical choice of  $\phi(r)$

-> Fundamental solution of Biharmonic equation  $\nabla^4 \phi = 0$

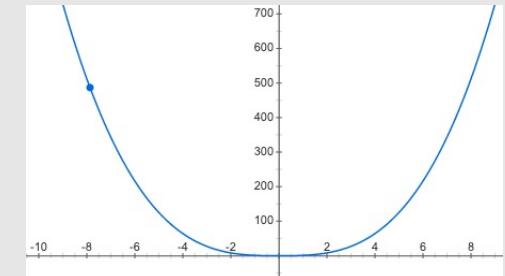
1D:  $\phi(r) = r$



2D:  $\phi(r) = r^2 \ln(r)$



3D:  $\phi(r) = r^3$

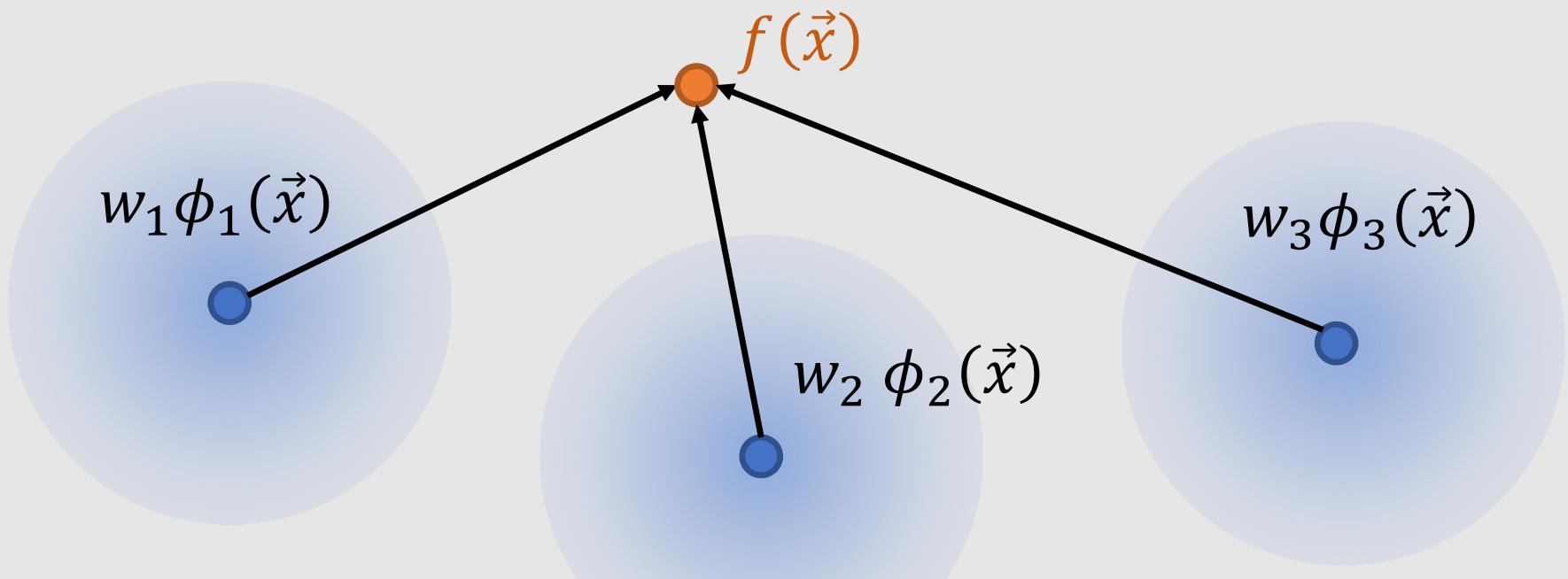


# Radial Based Function Interpolation

- The interpolation is weighted sum of the RBFs

$$f(\vec{x}) = \sum_{i \in N} w_i \phi(|\vec{x} - \vec{x}_i|)$$

How we can  
compute  $w_i$  ?



# Radial Based Function Interpolation



- The interpolation is weighted sum of the RBFs

$$f(\vec{x}) = \sum_{i \in N} w_i \phi(|\vec{x} - \vec{x}_i|)$$

How we can  
compute  $w_i$  ?

- Weighs are computed to satisfy constraints  $f(\vec{x}_i) = f_i$

$$\begin{bmatrix} \phi(|\vec{x}_1 - \vec{x}_1|) & \phi(|\vec{x}_1 - \vec{x}_2|) & \cdots & \phi(|\vec{x}_1 - \vec{x}_N|) \\ \phi(|\vec{x}_2 - \vec{x}_1|) & \phi(|\vec{x}_2 - \vec{x}_2|) & \cdots & \phi(|\vec{x}_2 - \vec{x}_N|) \\ \vdots & \vdots & \ddots & \vdots \\ \phi(|\vec{x}_N - \vec{x}_1|) & \phi(|\vec{x}_N - \vec{x}_2|) & \cdots & \phi(|\vec{x}_N - \vec{x}_N|) \end{bmatrix} \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_N \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ \vdots \\ f_N \end{pmatrix}$$

$\underbrace{\phantom{\begin{bmatrix} \phi(|\vec{x}_1 - \vec{x}_1|) & \phi(|\vec{x}_1 - \vec{x}_2|) & \cdots & \phi(|\vec{x}_1 - \vec{x}_N|) \\ \phi(|\vec{x}_2 - \vec{x}_1|) & \phi(|\vec{x}_2 - \vec{x}_2|) & \cdots & \phi(|\vec{x}_2 - \vec{x}_N|) \\ \vdots & \vdots & \ddots & \vdots \\ \phi(|\vec{x}_N - \vec{x}_1|) & \phi(|\vec{x}_N - \vec{x}_2|) & \cdots & \phi(|\vec{x}_N - \vec{x}_N|) \end{bmatrix}}_K \quad \underbrace{\begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_N \end{pmatrix}}_w = \underbrace{\begin{pmatrix} f_1 \\ f_2 \\ \vdots \\ f_N \end{pmatrix}}_f$

# Reference

- **Scattered Data Interpolation for Computer Graphics**, Ken Anjyo, J.P. Lewis, Frédéric Pighin, *Proceeding SIGGRAPH '14 ACM SIGGRAPH 2014 Courses Article No. 27*

[https://olm.co.jp/rd/research\\_event/scattered-data-interpolation-for-computer-graphics/?lang=en](https://olm.co.jp/rd/research_event/scattered-data-interpolation-for-computer-graphics/?lang=en)

