# **Collision Detection 2**

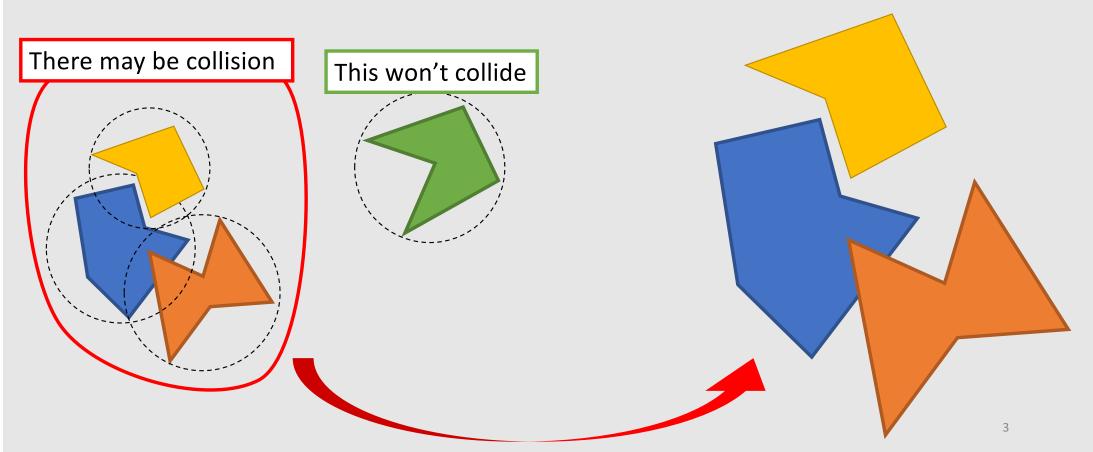
衝突検出

#### Collision between Triangle Meshes

• If there are N triangles, there are N(N-1)/2 number of pairs

## **Collision Detection in Two Stages**

Broad Phase: extract candidate Narrow Phase: actual check



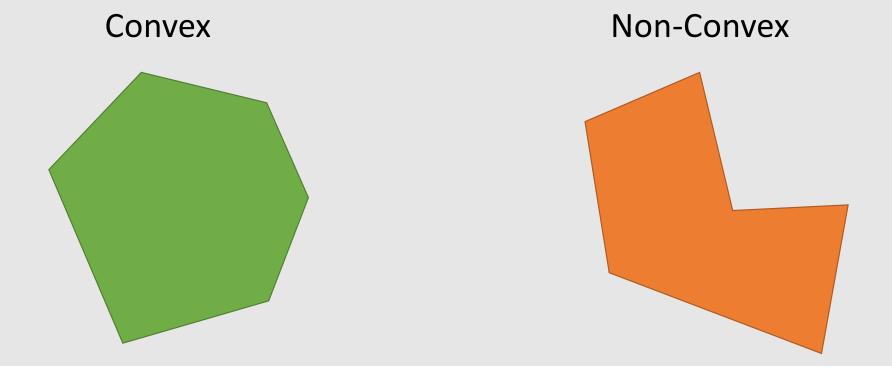
#### Garimpeiro for Finding Collision in a Mesh



# Narrow Phase Collision Detection

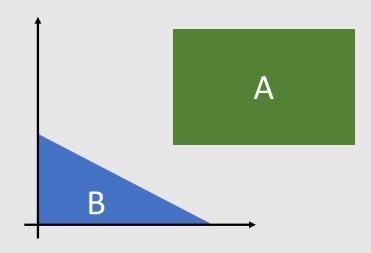
#### **Convex Shape**

Difference between "Convex" and "Non-Convex" shape?



#### Minkowski Sum (ミンコフスキー和)

$$A \oplus B = \{a + b | a \in A, b \in B\}$$



#### Minkowski Difference (ミンコフスキー差)

$$A \ominus B = \{a - b | a \in A, b \in B\}$$

## Gilbert-Johnson-Keerthi (GJK) Algorithm

# **Separation Theory**

## **Collision of Two Triangles**

Three patterns

#### **Continuous Collision Detection (CCD)**

CCD is a must for thin objects (e.g., shell, rod)

#### Sturm's Theorem